

Movement behaviour and video tracking of *Milnesium tardigradum* Doyère, 1840 (Eutardigrada, Apochela)

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Abstract

Tardigrades or ‘water-bears’ live in moist environments with a high degree of gaseous exchange. In tardigrades, locomotion is essential, e.g. for feeding, to find sexual partners and to adjust the level of hydration by moving to wetter or dryer environments. Here we report on the movement behaviour of *Milnesium tardigradum* in automated experiments using custom-made video tracking software. The experiments involved 754 hours of recording involving 32 individuals. No significant differences in mobility were observed under infrared versus visible light conditions, representing night and day, respectively. The mean recorded velocity was 23.3 ± 7.38 mm/h, with a maximum of 1166.4 mm/h.

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Introduction

In recent years the phylum Tardigrada has been expanded by several new taxa and increased to more than 960 species, but the number of described species still increases quickly every year (Guidetti and Bertolani, 2005; Degma and Guidetti, 2007). Despite their overall abundance tardigrades have received little scientific attention, particularly their physiology and behaviour, in the last 200 years. The name tardigrade describes

their movement (Lat. tardus-slow, gradi-walker) and was assigned in the 18th century by Lazzaro Spallanzani, who also carried out pioneer studies on their ‘resurrection’ (cryptobiosis) (Spallanzani, 1776).

Although there are several studies on tardigrades to understand the mechanisms of dehydration and freezing in embryonic and adult specimens (Ramløv and Westh, 1992; Westh and Kristensen, 1992; Sømme, 1996; Jönsson, 2001; Jönsson *et al.*, 2001; Wright, 2001; Nelson, 2002; Rebecchi *et al.*, 2006; Hengherr *et al.*, 2008, 2009a, 2009b; Schill and Fritz, 2008; Schill *et al.*, 2009), only limited data have been generated to understand their ecology. In addition, little attention has been devoted to the life-history of tardigrades (Von Wenck, 1914; Baumann, 1961, 1964, 1966, 1970; Dougherty, 1964; Suzuki, 2003; Altiero *et al.*, 2006) and their adaptive behaviour (Nelson and Adkins, 2001; Wright, 2001; Xiaochen and Wang, 2005; Altiero *et al.*, 2006). Terrestrial tardigrades live in a thin film of water on the surface of moss, lichens, algae, and other plants and depend on water to remain active and complete their life cycle. In these habitats tardigrades can survive desiccation during dry spells by contracting into a regular-shaped ‘tun’ state (Baumann, 1922, 1927). However, this can only occur when they are slowly dehydrated within an environment of high humidity (Crowe, 1975). Thus locomotion in fast changing microhabitats is the single most important determinant of animal behaviour to control dehydration and rehydration. In addition, *Milnesium tardigradum* Doyère, 1840 and *Macrobiotus richtersi* Murray, 1911 actively hunt their prey (Hohberg and Traunspurger, 2005; Hengherr *et al.*, 2008).

Observation of motion and locomotion patterns in their natural habitat is not possible. However, previous studies with artificial or at best semi-natural conditions were performed in the late 1920s by Marcus (1928), who estimated the maximal rate of movement at 30-50

$\mu\text{m/s}$ for *Echiniscus* and $100 \mu\text{m/s}$ for *Batillipes* and *Milnesium*. Later observations by videotaping were carried out to investigate the movement behaviour of *Macrobiotus* sp. and *Echiniscus testudo* (Doyère, 1840) on single stems of mosses with differing water retaining capacities and to observe the general pattern of tardigrade leg movement (Schüttler and Greven, 2000/2001). To understand the life-history and habitat preferences of terrestrial tardigrades it is, however, necessary to acquire data from behavioural experiments. We therefore focused our study on speed and direction of the locomotion in an artificial system during simulated day and night conditions for the tardigrade species *M. tardigradum*.

Material and methods

Organisms

Tardigrades of the species *M. tardigradum* Doyère, 1840 (Eutardigrada, Apochela) were cultured in the laboratory in plastic culture dishes with a thin layer of agar, covered with Volvic™ water (Danone Waters Deutschland, Wiesbaden, Germany). The animals were fed rotifers of the species *Philodina citrina* Ehrenberg, 1832 which were raised on the green algae *Chlorogonium elongatum* (Dangeard, 1897). Young tardigrades were additionally fed green algae *C. elongatum*. We used animals from a parthenogenetic population,

which was previously collected in Tübingen, Germany, and cultured over several years in an environmental chamber at 20°C using an artificial light source with a 12 h light/12 h dark cycle. The age of the tested tardigrades was approximately 40 days and the animals had a mean body size of about 1 mm.

Experimental platform

For the behavioural experiments and the observation of the specimens a simple ‘arena’ construction was developed (Fig. 1). For this purpose 36 openings were drilled through a plexiglas plate to form the arena grid, with each individual ‘arena’ having a diameter of 7 mm. Preliminary tests showed that the optimal adhesive material for fixing the ‘arena’ grid was hot paraffin wax. The surface of paraffin is rough (not slippery as normal Petri dishes), so this material seemed to be suitable for the movement of tardigrades using their clawed limbs without further adaptation.

Behavioural experiments

The behavioural experiments were carried out in a room with constant climate conditions controlled by a climate control system and using a video tracking system. For the experiments the Petri dish with arena grid was positioned on a custom-made infrared light table and filled with Volvic™ water (Fig. 1). Thereafter, well fed animals were placed individually into each ‘arena’,

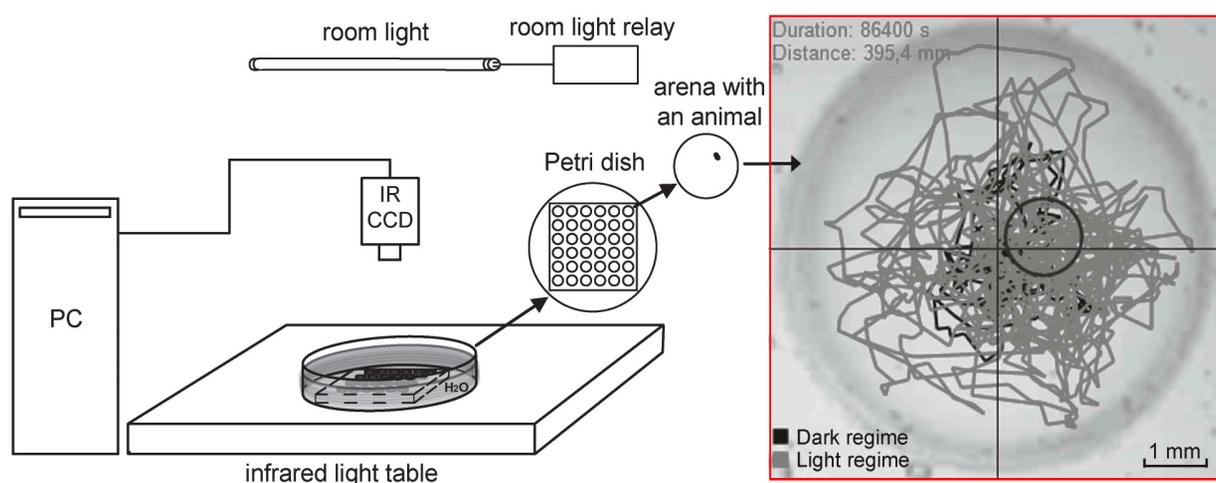


Fig. 1. Schematic representation of a video tracking system for the automated analysis of animal movement behaviour. The right part of the figure shows an example trajectory of an individual of *M. tardigradum* over the first 24-hour period. The circle indicates the last position of the animal (see embedded supplementary video).

Table 1a-b. a) Movement behaviour of *M. tardigradum* during the light and dark regime. b) Movement behaviour of *M. tardigradum* during the first and second periods of observation.

a) parameter	light regime	dark regime	number of animals
mean speed (mm/h)	19.8 ± 10.4	29.0 ± 11.1 n.s.	22
b) parameter	first observation period	second observation period	number of animals
spatial rate of change of direction (°/mm)	241.4 ± 21.3	180.6 ± 20.1***	31
mean speed (mm/h)	14.4 ± 7.6	31.0 ± 8.7**	31

and the behaviour of tardigrades was recorded using an infrared sensitive camcorder (Sony DCR–HC23E). For the duration of the experiments the infrared light table was left ON to produce the optimal illumination for the infrared camcorder. The only visible light (daytime) was emitted by a standard halogen lamp of type ‘Philips TLD 58 W’ with the colour temperature of 4000 K. The intensity of illumination in the experimental area was measured at 200 lux. The room lightning was controlled by an automated relay. The working mode of visible light was 12 h ON (light regime), 12 h OFF (dark regime). For capturing and saving of video information the freely available software VirtualDub (<http://www.virtualdub.org>) was used. The video was recorded directly to the hard drive of a computer system at 25 frames per second, and because of the small size of the animals (≤ 1 mm) it was possible to record two arenas simultaneously by one camcorder.

Video analysis and statistics

The sampled videos were analysed using the custom made video tracking software "BioMotionTrack D.S.", programmed by D. Shcherbakov. Analysis of animal movements by our video tracking program was based on an automated body contours recognition algorithm. The software calculated the location coordinates of the animals, their movement speed and length of the tracks, portion of time in different areas of the arenas, and angle of movement direction. Due to the very slow movement and speed of the animals it was sufficient to analyse 1 frame per 10 second of the original video source. A video file with the animal tracks was created as a result of this calculation (see Fig. 1, embedded supplementary video) and calculated data were saved as ‘.asc’-text. These results were imported into Access (Microsoft) database for data management and analysis. The calculation of statistical significance was carried out by Wilcoxon matched pairs test (Statistica 6.1

– StatSoft, Inc). Significance levels were $P \geq 0.05$ (not significant), $0.05 > P \geq 0.01$ (weakly significant *), $0.01 > P \geq 0.001$ (significant **), and $P < 0.001$ (highly significant ***).

Results

For the statistical analysis of the mean speed [mm/h] under light and dark regimes the results of 22 animals were used (Fig. 2, Table 1a), and for the spatial rate of direction change [°/mm] and the mean speed [mm/h] we divided the total period of observation into first and second intervals (Fig. 2). For this a total of 31 animals were observed (Table 1b).

Movement speed

The mean speed of tested animals during the first observation period was 14.4 ± 7.6 mm/h, and during the second period 31.0 ± 8.7 mm/h (Table 1b). The maximum total distance travelled by an individual was measured as 1,799.3 mm during 37 hours with a mean speed of 48.6 ± 8.99 mm/h. On the other hand, the fastest individual of *M. tardigradum* covered a distance of 1,365.6 mm during 6 hours with a mean speed of 227.6 ± 6.64 mm/h. One individual’s maximum burst of speed was measured at 1,166.4 mm/h for 10 seconds. In 24.8 % of the recorded time (187 hours) the animals showed no movement at all. During 64.3 % (485 hours) of the time recorded the mean speed was higher than 0 and ≤ 50 mm/h, while in the remaining 10.9 % (82 hours) of the time specimens were on average faster than 50 mm/h. Under the light regime tardigrades showed a mean speed of 19.8 ± 10.4 mm/h, and under infrared light illumination (dark regime) mean speed increased to 29.0 ± 11.1 mm/h (Table 1a). This difference, however, was not statistically significant ($p=0.14$), due mostly to the high variance between individual specimens.

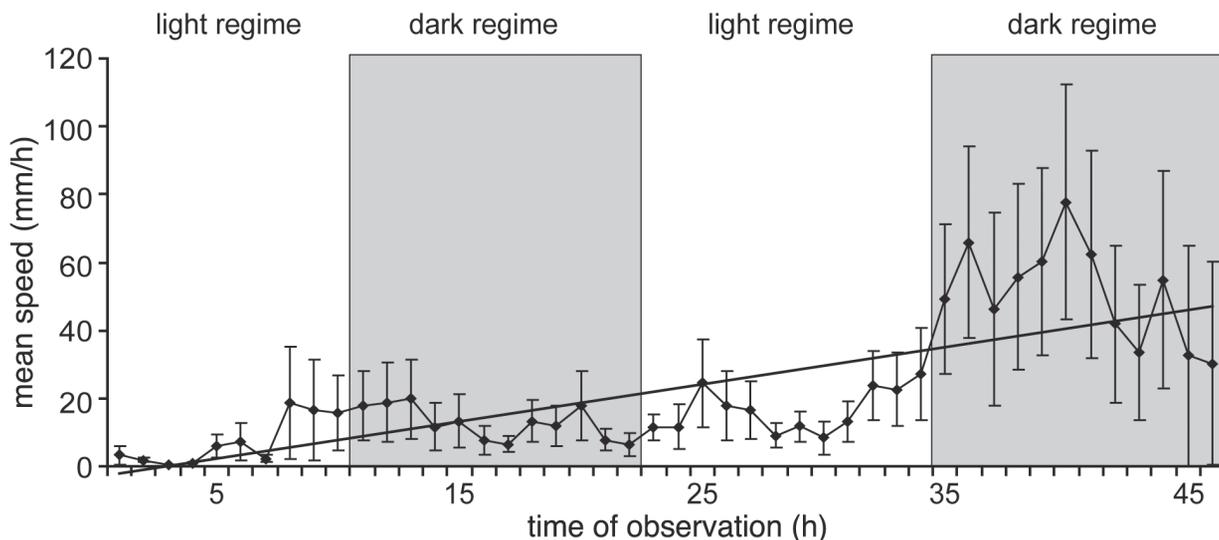


Fig. 2. The dynamics of movement activity for *M. tardigradum* are based on the analysis of 22 animals with light and dark regimes.

Dynamics of movement activity

The calculations for 31 individuals showed that after the first observation period the speed of movement increased (Table 1b), and this difference was statistically highly significant. For characterization of tardigrade movement directionality, the angles ($^{\circ}$) of direction changes between successive movements were calculated (turning angle). The mean summarized turning angles per hour for the second period were $3,067 \pm 631.62^{\circ}$, 1.8 times higher than in the first period ($1,667 \pm 511.88^{\circ}$). The animals changed direction more often with the increased movement activity of the second observation period. This increase in the mean summarized turning angles per hour was also statistically highly significant.

For the analysis of the rate of direction change (Benhamou and Bovet, 1989) the mean turning angle ($^{\circ}$) per mm of covered distance was calculated. During the first observation period the animals showed predominantly oscillating movements with a higher rate of direction change ($241.4 \pm 21.3^{\circ}/\text{mm}$). During the second observation period the rate of direction change was significantly lower ($180.6 \pm 20.1^{\circ}/\text{mm}$) (Table 1b).

Discussion

Marcus (1929) observed a positive phototactic response for the heterotardigrades *Batillipes mirus* Rich-

ters, 1909 and *Echiniscoides sigismundi* (Schultze, 1865) but negative phototaxis for the eutardigrade *Dactylobiotus dispar* (Murray, 1907). The intensity of light also seemed to be an important factor, because the eutardigrade *Pseudobiotus megalonyx* (Thulin, 1928) was more likely to show negative phototaxis to direct sunlight but positive phototaxis to more diffuse light. However, until now all published studies represent observations without an automatic long-term video tracking system, and the visual abilities of tardigrades are so far unknown.

In our experiments *M. tardigradum* showed a quite low mean speed during the whole period of observation ($23.3 \pm 7.38 \text{ mm/h} \approx 23$ body lengths/h), in perfect agreement with the Latin etymology of the phylum name - 'slow walker'. Nevertheless, the maximal burst of speed was quite high (1,166.4 mm/h) for an animal with such a small body size, *i.e.* they moved at ~ 1166 body lengths/h, although only for a very short time span of a few seconds. We suppose that the fast movements could be used by the animals to react quickly to environmental stimuli.

The reason for the different locomotion patterns and speed of individual animals is unclear. In just a quarter of the observation time *M. tardigradum* was passive and showed no mobility. As the animals were fed before the observation was started, the stimulation to move around for prey should be reduced. This phenomenon has also been reported for the species *M. richtersi* where some individuals after feeding on

nematodes had to rest for a variable amount of time, while other animals fed more slowly and continuously without a break (Hohberg and Traunspurger, 2005).

We observed that the movements of individual tardigrades accelerated twice after the first observation period, which may be explained by stimuli for motion, in this case most likely that of hunger. Analysis of the dynamics of the walking speed showed an orthokinetic form of movements, *i.e.* animals change their speed of movement depending on environmental stimuli. Thus under favourable conditions movement will be slower due to the absence of motivation to leave a preferred area. Similar examples for orthokinetic locomotion behaviour were observed for woodlice with their search for high humidity habitats (Fraenkel and Gunn, 1961) and by ants searching for feeding places (Drouot *et al.*, 2001).

The lower rate of direction change, shown after the first observation period, leads to straighter trajectories and thus allows an animal to leave an unfavourable area more quickly – in this case an area with no food. The change in the movement turning intensity ($^{\circ}/h$ and $^{\circ}/mm$) indicated a klinokinetic behaviour pattern by tardigrades. By klinokinesis animals change their frequency of movement direction depending on the environmental variability (Merkel, 1980). Our results are thus in agreement with the observation that animals show an increase in rate of direction change to stay within a more favourable area and decrease rate of direction change to move away from an unfavourable area (Codling *et al.*, 2008).

In *M. tardigradum*, the analysis of the automated tracking did not reveal any significant differences between the movement speed during the light and dark regimes. This does not mean that light conditions have no effect on the movement activities of this species, but rather the animals can be very active under both light conditions and show no light dependent resting period. Young individuals of the species *Macrobotus* cf. *hufelandi* exhibited a negative response to light, while animals larger than 120 μm exhibit neither negative or positive responses (Beasley, 2001). Beasley assumed that animals smaller than 120 μm avoid light to protect themselves from desiccation due to the disadvantageous surface area-to-volume ratio. We have not tested whether young animals of *M. tardigradum* show similar behaviour, but their ability to cope with desiccation is already developed in embryos (Schill and Fritz, 2008), so it could be possible.

We feel this study revealed novel insights in the ecology and behaviour of *M. tardigradum*, and the use of an automated video tracking system opens a wide

range of possibilities for future behavioural studies on other members of this phylum.

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